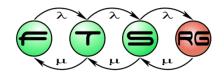
# Testing the robustness and safety of context-aware autonomous behavior

Research Report

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#### Outline

- Motivations and applications
- The testing concept
- Context modeling
- Requirements modeling
- Test strategies
- Test evaluation
- Summary





#### Introduction

- Ongoing research activity
  - Development of methods and tools for the efficient verification and testing of dependable and safety-critical systems



- Autonomous systems
  - that make decisions to execute missions without direct human control
- Context-aware systems
  - that use perceived context information to provide relevant services









# Objectives and applications

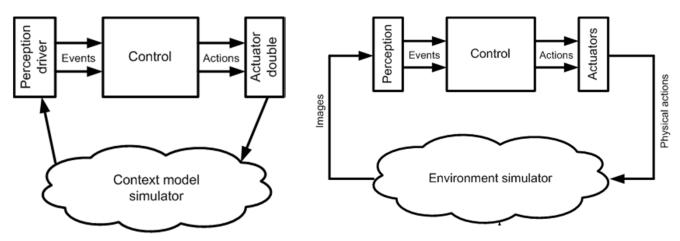
- Objectives of testing
  - Robustness and safety: safe system behavior in the presence of stressful environmental conditions
  - Context-awareness: dependency of the system behavior on the evolving state of the complex environment (context)
- Systems to be tested in the project
  - Autonomous robots: household and manufacturing
  - Autonomous vehicles: LGV, UAV, RUAV
- Typical safety requirements to be addressed
  - "In case the robot is in close proximity to living beings it shall send sound or voice alerts"
  - "When an obstacle gets to the dangerous area then the vehicle shall stop"
  - → Context-related conditions (initial, interim and final), and corresponding sequence of actions



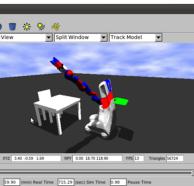


# Test purpose and challenges

Black-box testing of the control functions







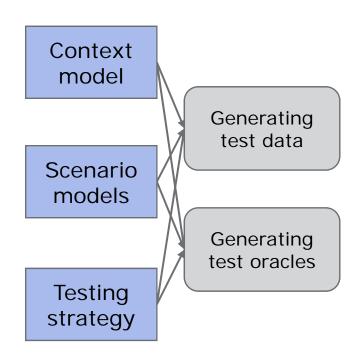
- Simulator: Context can be configured, and actions can be observed during a mission
- Challenges
  - Complex context, large number of possible situations
  - Informal requirements
  - Ad-hoc test data
  - $\circ$  Lack of test quality metrics  $\rightarrow$  Coverage metrics
- → Precise representation
  - → Systematic robustness testing





#### Testing concept

- Test goals
  - Systematic generation of test data,
     i.e., test contexts that include stressful (unexpected) situations
  - Evaluating the safety of the observed behavior
- What is needed?
  - Description of the environment:
     Context modeling
  - Capturing the test requirements:
     Scenario modeling
  - Systematic generation of test data:
     Testing strategies
- Tools for the tedious steps

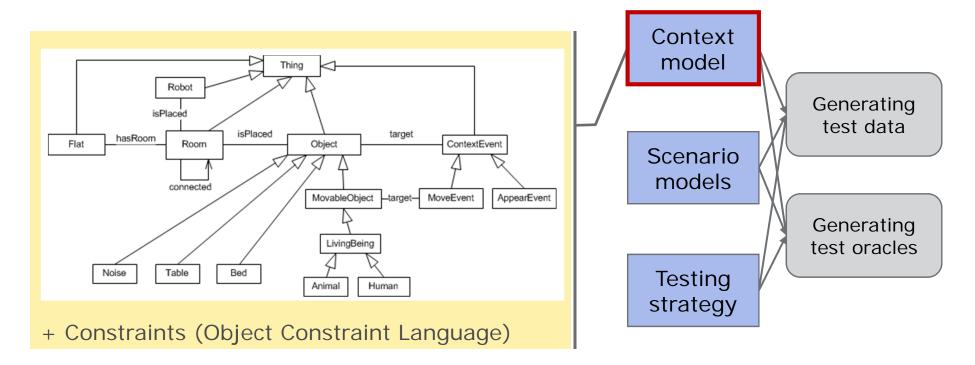






#### Context modeling

- Domain ontology → Context metamodel
  - Objects with properties, including dynamic objects
  - Relations: concrete or abstract relations
  - Constraints: physical limitations and application-specific constraints
- Action model for control actions

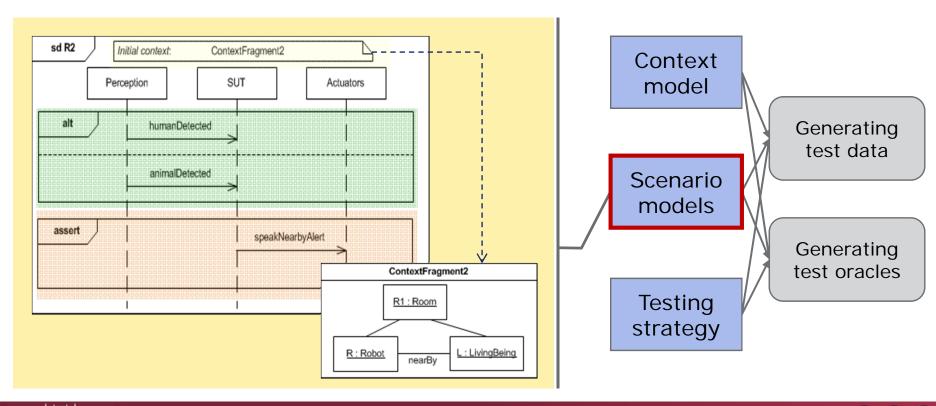






## Scenario modeling

- Safety requirements → Scenario model
  - Initial context fragment: instances of the context metamodel
  - Condition part: Events (perception) and messages (commands)
  - Assertion part: Expected or forbidden actions and context changes
  - Precise semantics based on MSC and LSC constructs with time



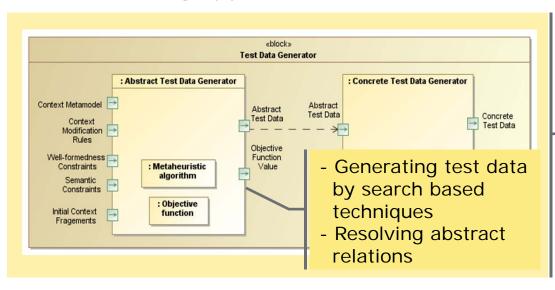


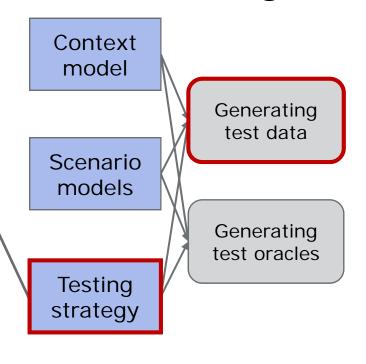


## Strategies for testing robustness

- Unexpected objects  $\rightarrow$  context coverage

  - Extending the initial context fragment with extra objects
- Complex contexts
- → scenario coverage
- Combining (n-wise) the initial context fragments of scenarios
- - Mutating initial context fragments: using boundary values of properties, violating application constraints









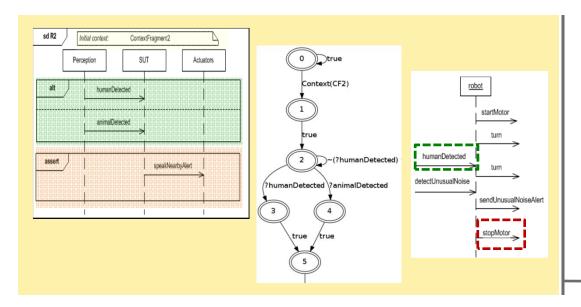
## Evaluating test traces

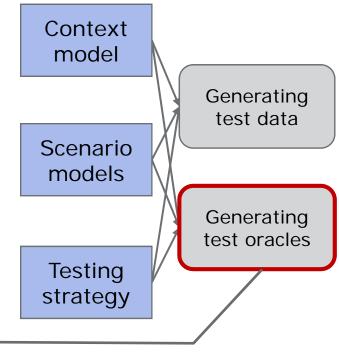
 Evaluating a test trace simultaneously against each requirement scenario, from each relevant step

 Matching events and context changes (respecting object hierarchy): using efficient graph-based decomposition techniques

 Automated evaluation of traces: synthesis of observer automata from the scenarios

o Identifying violated scenarios → metrics









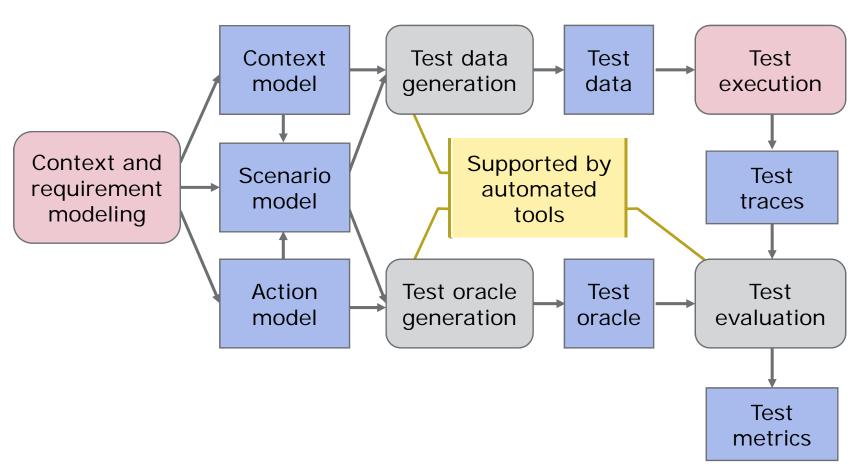
# Example: Combining initial contexts

Test requirement scenarios: Test trace: <u>robot</u> ContextFragment1 ContextFragment1 startMotor Perception Actuators R1:Room detectUnusualNoise humanDetected AE: AppearEvent R: Robot N: Noise detectUnusualNoise sendUnusualNoiseAlert sendUnusualNoiseAlert stopMotor **Evaluation:** sd R2 Initial context: ContextFragment2 robot ContextFragment2 Actuators R1: Room startMotor humanDetected turn ME: L: LivingBeing MoveEvent animalDetected humanDetected detectUnusualNoise speakNearbyAlert sendUnusualNoiseAlert Test verdict: a1: AppearEvent Test data n1: Noise f1: Flat -hasRoomr2:Room R3 passed generated: R2 failed hugo: Robot m1: MoveEvent h2: Human





## The testing method



- Lightweight but precise requirement modeling
- Automated tools to support test generation and evaluation





#### Summary

- Model based robustness testing approach
  - o Context modeling: "What is possible?"
  - Scenario modeling: "What is required?"
  - o Initial context fragment: "What is relevant?"
  - Testing strategy: "What is stressful?"
- Developing methods and tools
  - Context and requirements modeling
  - Generating test data for testing robustness and safety of the context-aware behavior
  - Generating test oracles for test evaluation
- Applications and ongoing validation
  - Household robot (ROS based simulator)
  - Laser guided forklift (real configurations)







